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Corso di Laurea in Ingegneria Elettronica e Informatica

Prova Intracorso AA 2021-22 (unica)

Teoria dei Segnali

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giovedì 2 Dicembre 2021

## SOLUZIONI

1. Schizzare i seguenti segnali e valutarne l'energia, la potenza e la trasformata di Fourier:

- (a)[3 pt]  $s(t) = \Pi\left(\frac{t-3}{6}\right) + 2\Lambda(t-3); \quad \checkmark$
- (b)[3 pt]  $s(t) = (e^{-2t} + e^{-4t})u(t);$
- (c)[3 pt]  $s(t) = 1 - \cos\frac{\pi}{2}t + \cos^2 2\pi t.$
- (d)[4 pt]  $s(t) = \sum_{k=-\infty}^{\infty} \Lambda(t-1-3k) \quad \checkmark$

2.[10 pt] Usando il metodo grafico valutare la risposta nel dominio del tempo di un sistema lineare (anticausale) avente risposta impulsiva  $h(t) = e^{\alpha t}u(-t)$  al cui ingresso è posto il segnale  $s(t) = u(t-1) - u(t-3).$

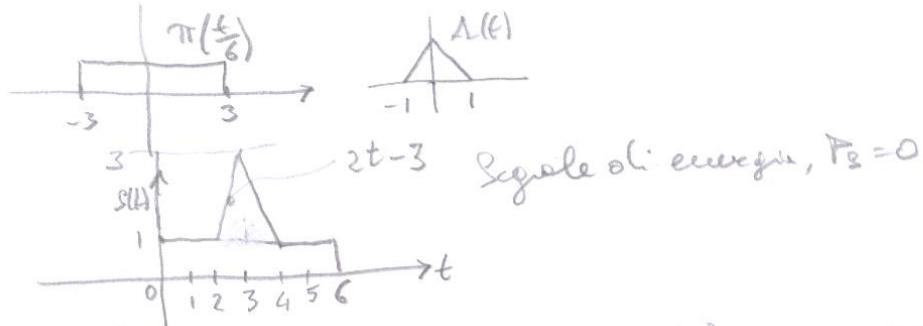
3.[10 pt] Si consideri il segnale aleatorio

$$s(t) = A + x(t) + x(t) \cos(\pi Bt + \Theta) \quad (1)$$

dove  $A$  è una costante deterministica,  $x(t)$  è un processo aleatorio SSL a media nulla con spettro di potenza  $P_x(f) = \Pi\left(\frac{f}{B}\right)$  e  $\Theta$  è una variabile aleatoria uniformemente distribuita in  $[-\pi, \pi]$ . Calcolare la autocorrelazione di  $s(t)$  e studiarne la stazionarietà. In caso di stazionarietà calcolarne anche lo spettro di potenza.

4.[10 pt] Due segnali passa-basso con frequenza massima  $B$ , modulano in fase e in quadratura (QAM) una portante a frequenza  $f_0$ . Schizzare lo spettro approssimativo del segnale modulato. Usando l'espressione analitica del segnale modulato, valutare le uscite del demodulatore coerente in presenza di un errore di fase nell'oscillatore locale pari a  $\theta$ .

1. a)  $s(t) = \pi\left(\frac{t-3}{6}\right) + 2\Delta(t-3)$  ②

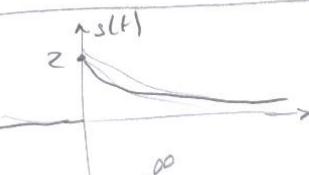


$$\begin{aligned} E_s &= \int_0^6 s^e(t) dt = 2 \int_0^2 1 dt + 2 \int_2^3 (2t-3)^2 dt = 4 + 2 \int_2^3 (4t^2 - 12t + 9) dt \\ &= 4 + 2 \left[ 4 \frac{t^3}{3} \Big|_2^3 - 12 \frac{t^2}{2} \Big|_2^3 + 9t \Big|_2^3 \right] \\ &= 4 + 2 \left[ 4 \frac{27-8}{3} - 12 \frac{9-4}{2} + 9(3-2) \right] \\ &= 4 + 2 \left[ \frac{4 \cdot 19}{3} - \frac{12 \cdot 5}{2} + 9 \right] = 4 + 2 \frac{8 \cdot 19 - 3 \cdot 12 + 54}{6 \cdot 3} \\ &= \frac{12 + 8 \cdot 19 - 15 \cdot 12 + 54}{3} = \frac{12 + 152 - 180 + 54}{3} = \frac{38}{3} \end{aligned}$$

$$S(f) = e^{-j2\pi f s} 6 \sin 6f + 2 e^{j2\pi f s} \sin^2 f$$

(b)  $s(t) = (e^{-2t} + e^{-4t}) u(t)$

Segnale di energia,  $P_s = 0$



$$\begin{aligned} E_s &= \int_0^\infty s^2(t) dt = \int_0^\infty (e^{-2t} + e^{-4t})^2 dt = \int_0^\infty e^{-4t} dt + \int_0^\infty e^{-8t} dt + 2 \int_0^\infty e^{-6t} dt \\ &= \left[ \frac{e^{-4t}}{-4} \right]_0^\infty + \left[ \frac{e^{-8t}}{-8} \right]_0^\infty + 2 \left[ \frac{e^{-6t}}{-6} \right]_0^\infty = \frac{1}{4} + \frac{1}{8} + \frac{1}{3} = \frac{6+3+8}{24} = \frac{17}{24} \end{aligned}$$

$$x(t) = e^{-\alpha t} u(t) \quad \xleftrightarrow{\text{FT}} \quad X(f) = \int_0^\infty e^{-\alpha t} e^{j2\pi f t} dt = \int_0^\infty e^{-(\alpha + j2\pi f)t} dt \quad (3)$$

$$= \frac{e^{-(\alpha + j2\pi f)t}}{-(\alpha + j2\pi f)} \Big|_0^\infty = \frac{1}{\alpha + j2\pi f}$$

$$S(f) = \frac{1}{2 + j2\pi f} + \frac{1}{4 + j2\pi f}$$

$$(c) s(t) = 1 - \cos \frac{\pi}{2}t + \cos^2 2\pi t = 1 - \cos \frac{\pi}{2}t + \frac{1}{2} + \frac{1}{2} \cos 4\pi t$$

$$s(t) = \frac{3}{2} - \cos \frac{\pi}{2}t + \frac{1}{2} \cos 4\pi t \quad \begin{matrix} \text{Segnale di potenza} \\ E_s = \infty \end{matrix}$$

$$P_s = \frac{9}{4} + \frac{1}{2} + \frac{1}{8} = \frac{18+4+1}{8} = \frac{23}{8}$$

$$S(f) = \frac{3}{2} \delta(f) + \frac{1}{2} \delta(f - \frac{1}{4}) + \frac{1}{2} \delta(f + \frac{1}{4}) + \frac{1}{4} \delta(f - 2) + \frac{1}{4} \delta(f + 2)$$

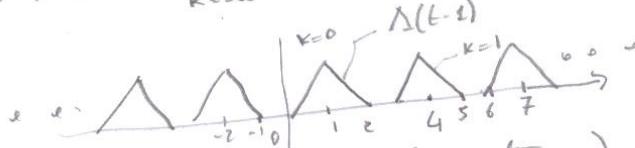
Note:

•  $\cos \frac{\pi}{2}t$  ha freq.  $\frac{1}{4}$

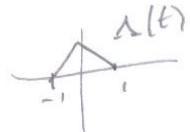
$$2\pi f_0 = \frac{\pi}{2} \Rightarrow f_0 = \frac{1}{4}$$

•  $\cos 4\pi t$  ha freq. 2

$$(d) s(t) = \sum_{k=-\infty}^{+\infty} \Delta(t-1-3k)$$



Segnale periodico (di potenza)



$$P_s = \frac{E(\Delta(t))}{T} = \frac{\frac{2}{3} \cdot \frac{1}{3}}{3} = \frac{2}{81}$$

Percorso T=3

$$s(t) = \Delta(t-1) * \sum_{k=-\infty}^{+\infty} \delta(t-3k)$$

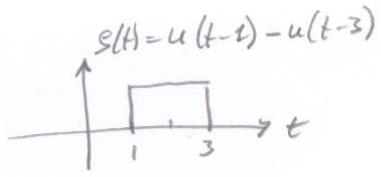
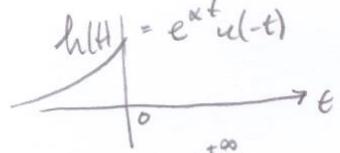
$$S(f) = \mathcal{F}[\Delta(t-1)] \cdot \mathcal{F}\left[\sum_{k=-\infty}^{+\infty} \delta(t-3k)\right]$$

$$= e^{-j2\pi f} \sin^2 f \cdot \frac{1}{3} \sum_{m=-\infty}^{+\infty} \delta(f - \frac{m}{3})$$

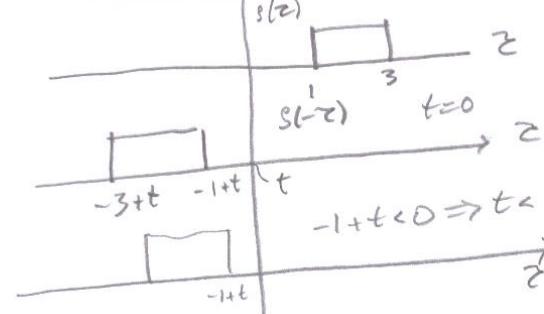
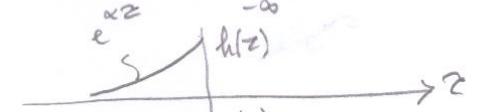
$$= \frac{1}{3} \sum_{m=-\infty}^{+\infty} e^{-j\frac{2\pi m}{3}} \sin^2 \frac{m}{3} \delta(f - \frac{m}{3}) \quad \begin{matrix} \text{Spettro a} \\ \text{triplo} \end{matrix}$$

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2.

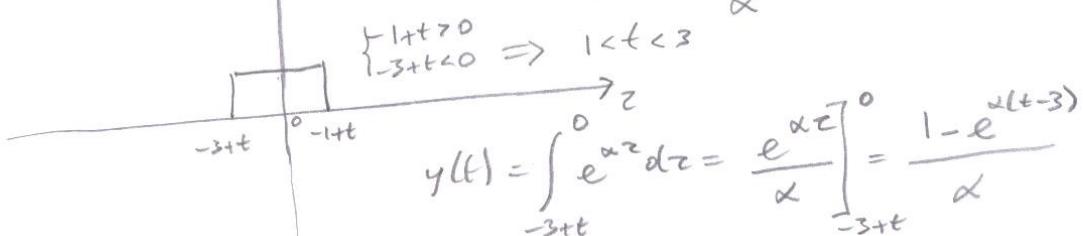


$$y(t) = (h * s)(t) = \int_{-\infty}^{+\infty} h(z) \times (t-z) dz$$

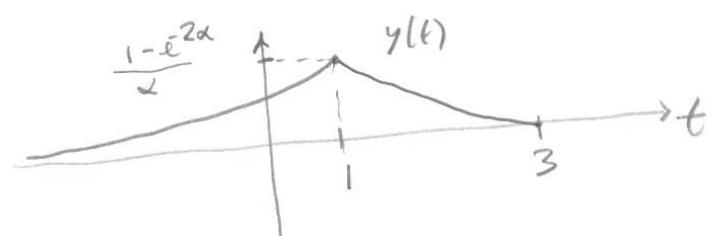
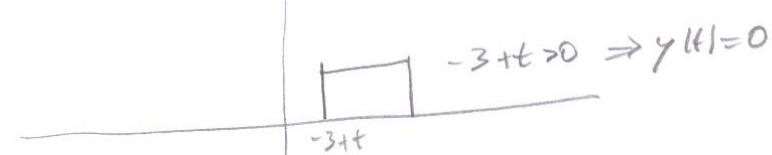


$$y(t) = \int_{-3+t}^{-1+t} e^{\alpha z} dz = \frac{e^{\alpha z}}{\alpha} \Big|_{-3+t}^{-1+t}$$

$$= \frac{e^{\alpha(t-1)} - e^{\alpha(t-3)}}{\alpha}$$



$$y(t) = \int_{-3+t}^0 e^{\alpha z} dz = \frac{e^{\alpha z}}{\alpha} \Big|_{-3+t}^0 = \frac{1 - e^{\alpha(t-3)}}{\alpha}$$



(5)

$$3. \quad s(t) = A + x(t) + x(t) \cos(\pi B t + \theta)$$

↑  
coh.

 $x(t) \text{ s.s.l}$ 

$$P_x(f) = \frac{\pi}{B} \left( \frac{f}{B} \right)$$

$$\theta \in \mathbb{D}(-\pi, \pi)$$

$$\begin{aligned}
 R_s(t, \tau) &= E[s(t)s(t-\tau)] = \\
 &E[(A + x(t) + x(t) \cos(\pi B t + \theta))(A + x(t-\tau) + x(t-\tau) \cos(\pi B(t-\tau) + \theta))] \\
 &= E[A^2] + E[Ax(t-\tau)] + E[Ax(t-\tau) \cos(\pi B(t-\tau) + \theta)] \\
 &\quad + E[x(t)A] + E[x(t)x(t-\tau)] + E[x(t)x(t-\tau) \cos(\pi B(t-\tau) + \theta)] \\
 &\quad + E[Ax(t) \cos(\pi B t + \theta)] + E[x(t)x(t-\tau) \cos(\pi B t + \theta)] + E[x(t)x(t-\tau) \cos(\pi B t + \theta) \\
 &\quad \quad \quad \cos(\pi B(t-\tau) + \theta)] \\
 &= A^2 + A E[x(t-\tau)] + A E[x(t-\tau)] E[\cos(\pi B(t-\tau) + \theta)] \\
 &\quad + A E[x(t)] + R_x(\tau) + \underbrace{E[x(t)x(t-\tau)]}_{R_x(\tau)} E[\cos(\pi B(t-\tau) + \theta)] \\
 &\quad + A E[x(t)] E[\cos(\pi B t + \theta)] + \underbrace{E[x(t)x(t-\tau)]}_{R_x(\tau)} E[\cos(\pi B t + \theta)] + \\
 &\quad \quad \quad \underbrace{E[x(t)x(t-\tau)]}_{R_x(\tau)} E\left[\frac{1}{2} \cos(\pi B(2t-\tau) + 2\theta) + \frac{1}{2} \cos \pi B \tau\right] \\
 &\quad \quad \quad \text{redondo m.d} \\
 &= A^2 + R_x(\tau) + R_x(\tau) E[\cos(\pi B(t-\tau) + \theta)] + R_x(\tau) E[\cos(\pi B t + \theta)] \\
 &\quad + \underbrace{R_x(\tau) E[\cos(\pi B(2t-\tau) + 2\theta)]}_{\frac{R_x(\tau)}{2}} + \frac{R_x(\tau)}{2} \cos \pi B \tau \\
 &= A^2 + R_x(\tau) + \frac{R_x(\tau)}{2} \cos \pi B \tau \quad \begin{matrix} \checkmark \\ \text{faz. } \frac{B}{2} \\ \text{processo s.s.l} \end{matrix} \\
 P_s(f) &= A^2 \delta(f) + P_x(f) + \frac{P_x(f - \frac{B}{2})}{4} + \frac{P_x(f + \frac{B}{2})}{4}
 \end{aligned}$$

4.

$s_1(t)$

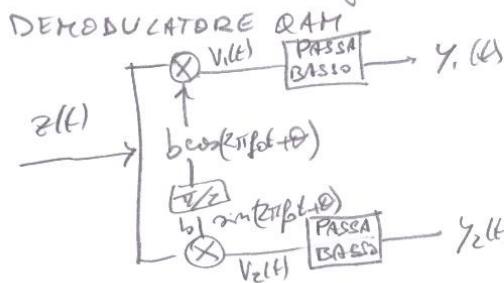
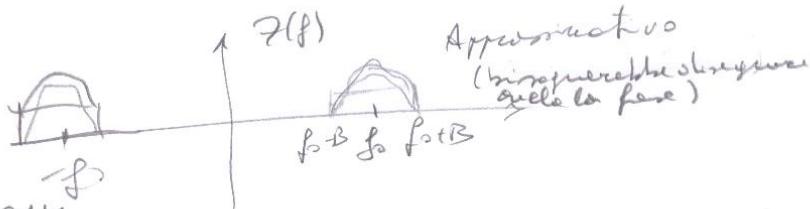
$s_2(t)$



⑥

$z(t) = s_1(t) \cos 2\pi f_0 t + s_2(t) \sin 2\pi f_0 t$

$z(f) = \frac{1}{2} s_1(f-f_0) + \frac{1}{2} s_1(f+f_0) + \frac{1}{2j} s_2(f-f_0) - \frac{1}{2j} s_2(f+f_0)$



$$\begin{aligned} v_1(t) &= z(t) b \cos(2\pi f_0 t + \theta) = (s_1(t) \cos 2\pi f_0 t + s_2(t) \sin 2\pi f_0 t) b \cos(2\pi f_0 t + \theta) \\ &= b \frac{s_1(t)}{2} \cos(2\pi f_0 2t + \theta) + b \frac{s_1(t)}{2} \cos \theta + b \frac{s_2(t)}{2} \sin(2\pi f_0 2t + \theta) \\ &\quad + b \frac{s_2(t)}{2} \sin(-\theta) \end{aligned}$$

$$\boxed{y_1(t) = \frac{b}{2} s_1(t) \cos \theta - \frac{b}{2} s_2(t) \sin \theta}$$

$$\begin{aligned} v_2(t) &= z(t) b \sin(2\pi f_0 t + \theta) = (s_1(t) \cos 2\pi f_0 t + s_2(t) \sin 2\pi f_0 t) b \sin(2\pi f_0 t + \theta) \\ &= b \frac{s_1(t)}{2} \sin(2\pi f_0 2t + \theta) + b \frac{s_1(t)}{2} \sin \theta + b \frac{s_2(t)}{2} \cos(2\pi f_0 2t + \theta) \\ &\quad + b \frac{s_2(t)}{2} \cos(-\theta) \end{aligned}$$

$$\boxed{y_2(t) = \frac{b}{2} s_1(t) \sin \theta + \frac{b}{2} s_2(t) \cos \theta}$$

I due segnali sono mescolati.  
 $\theta = 0$  perfettamente separati.  
 $\theta = \frac{\pi}{2}$  invertiti nelle uscite.